

Lecture 41

Encodings (contd.), Computers vs Turing machine, Halting Problem

Too Many Problems, Too Few TMs

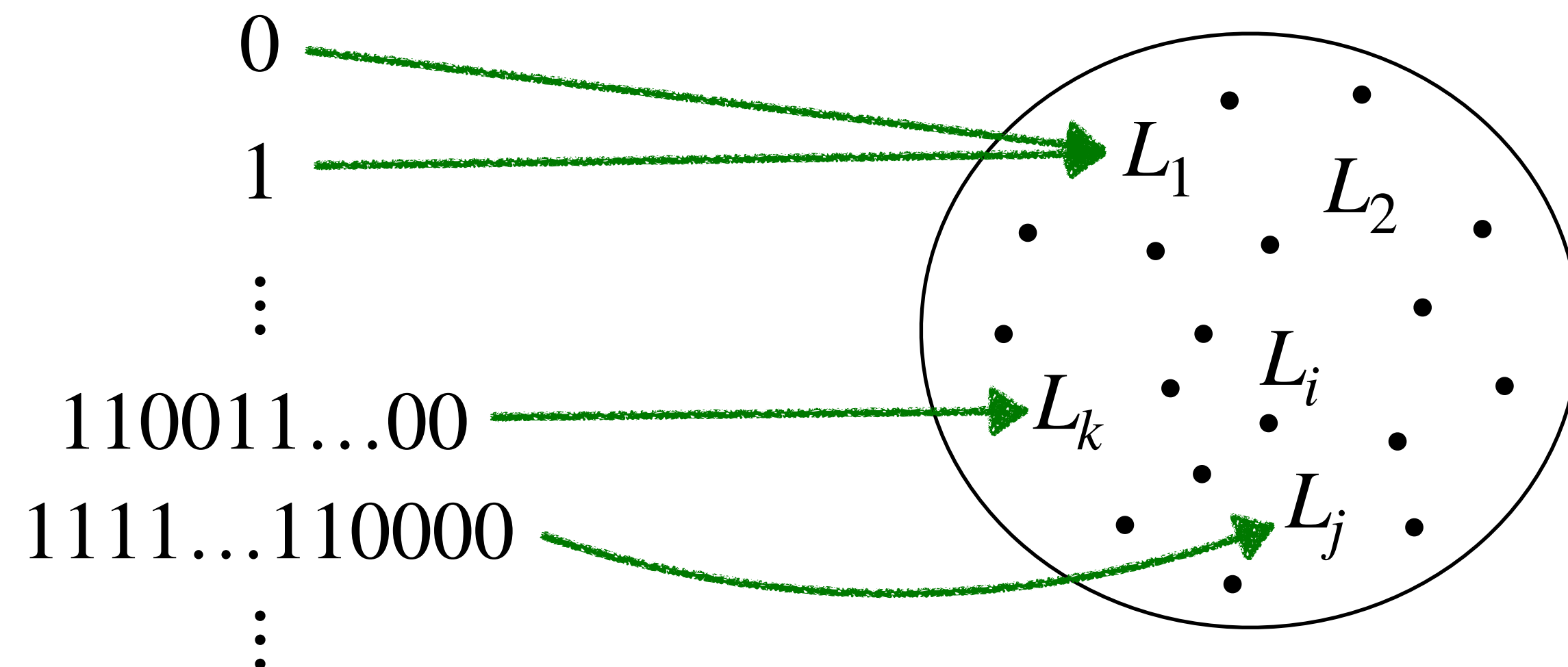
Notations:

- ▶ For any $\alpha \in \{0,1\}^*$, M_α denotes the TM whose encoding is α .
- ▶ $\langle M \rangle$ denotes the encoding of a TM M .
- ▶ $L(M)$ denotes the language of a TM M , i.e., the set of inputs that are accepted by M .

Theorem: There exist languages that cannot be decided/recognised by any TM.

Proof Sketch:

*Multiset of TMs
(Countable infinite)*



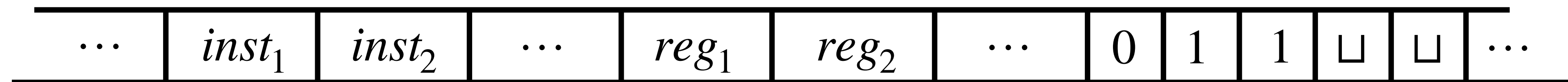
*Set of languages
(Uncountable)*

Computer vs Turing Machine

Simulating a Computer by Turing machine

High-level language programs can be translated into an assembly language program which is a finite sequence of instructions of type:

- ▶ Move data from memory into registers or vice-versa.
- ▶ Add or multiply the content of two registers into some register.



Assembly language program can be simulated in a TM by:

- ▶ Allocating portions of tape for registers and memory.
- ▶ Storing instructions on tapes.
- ▶ Executing instructions using δ .

Computer vs Turing Machine

Simulating a Turing machine by Computer

A C program with infinite memory can be written that simulates a Turing machine where:

- ▶ An infinite array can act as the tape of the TM.
- ▶ Transition function's entries can be stored in a finite 2-dimensional array.

Equal Power but Different Roles

- ▶ High-level languages are used to demonstrate an effective procedure that decides a given language because they are user-friendly.
- ▶ Turing machines are used to prove non-existence of an (efficient) effective procedure that decides a given language because of their simple mathematical structure.

Halting Problem

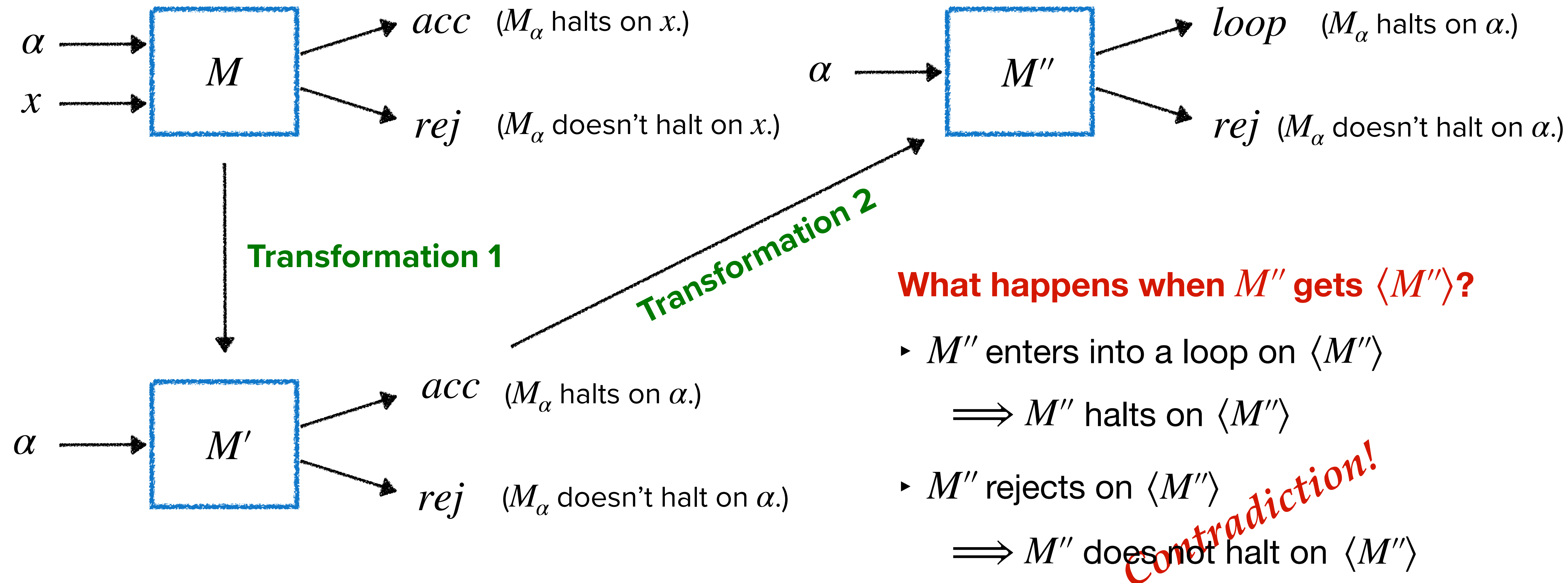
Definition: A TM that halts, i.e., either accepts or rejects, on every input is called a **Halting Turing Machine**.

Halting Problem: $\text{HALT} = \{(\alpha, x) \mid M_\alpha \text{ halts on input } x\}$

Theorem: HALT is undecidable.

Undecidability of HALT

Suppose a TM M decides $\text{HALT} = \{(\alpha, x) \mid M_\alpha \text{ halts on input } x\}$.



Recognising HALT

Theorem: $\text{HALT} = \{(\alpha, x) \mid M_\alpha \text{ halts on input } x\}$ is recognisable.

Proof: Consider a TM U that on input (α, x) :

- ▶ Starts simulating M_α on x .
- ▶ If M_α ever halts on x , U halts and accepts.
- ▶ If M_α never halts on x , U does not halt as well.

U uses portion of its tape as the tape of M_α and binary encoding to store symbols of M_α .

Clearly, $L(U) = \text{HALT}$.



The Big Picture

